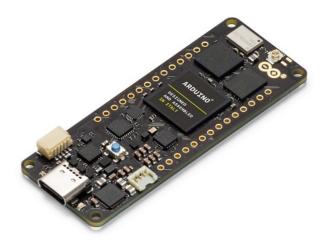
# 

# Distribuidor

Product Reference Manual SKU: ABX00042



### Description

The Portenta H7 is the first member of the Portenta family, dedicated to industrial use cases but with the traditional Arduino openness and ready for the most demanding Pro applications. The Portenta H7 is ready for machine learning and real-time applications thanks to the dual core STM32H747 processor including a Cortex® M7 running at 480 MHz and a Cortex® M4 running at 240 MHz. The two cores communicate via a Remote Procedure Call mechanism that allows calling functions on the other processor seamlessly for real multitasking. By harnessing the computational power of both Portenta H7's cores, machine learning algorithms can run simultaneously alongside low latency sensor/actuator interaction.

Arduino's expertise in producing high quality PCB in house has been leveraged to ensure that the Portenta H7 can meet the vibrations and temperatures met in daily industrial, automotive and agriculture applications. The various interfaces give the developers freedom in how they interact with the Portenta H7 and include MKR-compatible pins, USB-C enabled HDMI output and Arduino's open connector (ESLOV). Developers will receive the support they need from Arduino to build their custom solution.

Portenta H7 offers several customization possibilities that allow tailoring board functionality to specific applications for high volume use cases.

# 1 Configuration Options and Ordering Codes

Available assembly options that can be configured for high volume applications are the following:

Option	Description	Option Codes
SDRAM	external SDRAM memory	0 - None1 - 8 MByte2 - 16 MByte3 - 32 MByte4 - 64 MByte
FLASH	external QSPI Flash Memory	0 - None1 - 2 MByte (NOR)5 - 16 MByte (NOR)8 - 128 MByte (NAND)
Ethernet	10/100 Ethernet PHY	0 - NoneE - Fitted
HS USB	High Speed USB PHY	0 - NoneU - Fitted
Crypto	Crypto Chip	0 - NoneM - ATECC608AN - SE050C2B - Both
Wireless	Wireless Module	0 - NoneW - Fitted
Antenna	Antenna option	0 - NoneA - on board ceramic antennaC - U.FL connector
Video	DisplayPort output over USB-C	0 - NoneD - Fitted

Standard configurations are:

- Arduino Portenta H7-0000000 (barebones version)
- Arduino Portenta H7-15EUCWAD
  - 8MB SDRAM
  - 16MB NOR Flash
  - 10/100 Ethernet Phy
  - USB HS
  - NXP SE050C2 Crypto
  - Wi-Fi/BT Module
  - U.FL Antenna
  - DisplayPort over USB-C

### **Target Areas**



### Features

- \*\*ST STM32H747XI \*\*Processor
  - Dual core
    - Arm® Cortex®-M7 core at up to 480 MHz with double-precision FPU and 16K data + 16K instruction L1 cache
    - Arm® 32-bit Cortex®-M4 core at up to 240 MHz with FPU, Adaptive real-time accelerator (ART Accelerator™)
  - 2 Mbytes of Flash memory with read-while-write support + 1 Mbyte of RAM
  - Dual mode Quad-SPI memory interface running up to 133 MHz
  - CRC calculation unit
  - Security
  - ROP, PC-ROP, active tamper
  - 3 separate power domains which can be independently clock-gated or switched off:
    - D1: high-performance capabilities
    - D2: communication peripherals and timers
    - D3: reset/clock control/power management
  - Voltage scaling in Run and Stop mode (6 configurable ranges)
  - 2.95 μA in Standby mode (Backup SRAM OFF, RTC/LSE ON)
  - 4 DMA controllers to unload the CPU
  - 1× high-speed master direct memory access controller (MDMA) with linked list support
  - 2× dual-port DMAs with FIFO
  - 1× basic DMA with request router capabilities
  - Up to 35 communication peripherals
    - 4× I2Cs FM+ interfaces (SMBus/PMBus)
    - 4× USARTs/4x UARTs (ISO7816 interface, LIN, IrDA, up to 12.5 Mbit/s) and 1x LPUART
    - 6× SPIs, 3 with muxed duplex I2S audio class accuracy via internal audio PLL or external clock, 1x I2S in LP domain (up to 150 MHz)
    - 4x SAIs (serial audio interface)
    - SPDIFRX interface
    - SWPMI single-wire protocol master I/F
    - MDIO Slave interface
    - 2× SD/SDIO/MMC interfaces (up to 125 MHz)
    - 2× CAN controllers: 2 with CAN FD, 1 with time-triggered CAN (TT-CAN)
    - 2× USB OTG interfaces (1FS, 1HS/FS) crystal-less solution with LPM and BCD
    - Ethernet MAC interface with DMA controller
  - 8-bit camera interface (up to 80 MHz)
  - 11 analog peripherals
  - 3× ADCs with 16-bit max. resolution (up to 36 channels, up to 3.6 MSPS)
  - 1× temperature sensor
  - 2× 12-bit D/A converters (1 MHz)
  - 2× ultra-low-power comparators

- 2× operational amplifiers (7.3 MHz bandwidth)
- 1× digital filters for sigma delta modulator (DFSDM) with 8 channels/4 filters
- Graphics

🗩 PRO

- MIPI DSI host including an MIPI D-PHY to interface with low-pin count large displays
- Chrom-ART graphical hardware Accelerator<sup>™</sup> (DMA2D) to reduce CPU load
- Hardware JPEG Codec
- Up to 22 timers and watchdogs
- 1× high-resolution timer (2.1 ns max resolution)
- 2× 32-bit timers with up to 4 IC/OC/PWM or pulse counter and quadrature (incremental) encoder input (up to 240 MHz)
- 2× 16-bit advanced motor control timers (up to 240 MHz)
- 10× 16-bit general-purpose timers (up to 240 MHz)
- 5× 16-bit low-power timers (up to 240 MHz)
- 4× watchdogs (independent and window)
- 2× SysTick timers
- RTC with sub-second accuracy and hardware calendar
- True random number generators (3 oscillators each)
- 96-bit unique ID

#### External Memories

- up to 64 MByte SDRAM (optional)
- up to 128 MByte QSPI Flash (optional)
- USB-C
  - High Speed (optional)/Full Speed USB
  - DisplayPort output (optional)
  - Host and Device operation
  - Power Delivery support (optional)

#### High Density connectors

- 1x 10/100 Ethernet with PHY
- 1x CAN
- 4x UART (2 with flow control)
- 3x I2C
- 1x SDCard
- 1x SPI
- 1x I2S
- 1x PDM input
- 2 lane MIPI DSI output
- 8 bit parallel camera interface
- 10x PWM outputs
- 7x GPIO
- 8x ADC inputs with separate VREF
- Murata 1DX Wi-Fi/BT Module (optional)
  - Wi-Fi 802.11b/g/n 65 Mbps





- Bluetooth 5.1 BR/EDR/LE
- NXP SE050C2 Crypto (optional)
  - Common Criteria EAL 6+ certified up to OS level
  - RSA & ECC functionalities, high key length and future proof curves, such as brainpool, Edwards, and Montgomery
  - AES & 3DES encryption and decryption
  - HMAC, CMAC, SHA-1, SHA-224/256/384/512 operations
  - HKDF, MIFARE® KDF, PRF (TLS-PSK)
  - Support of main TPM functionalities
  - Secured flash user memory up to 50kB
  - I2C slave (High-speed mode, 3.4 Mbit/s), I2C master (Fast-mode, 400 kbit/s)
  - SCP03 (bus encryption and encrypted credential injection on applet and platform level)
- \*\*Microchip ATECC608 \*\*Crypto (optional)
  - Protected storage for up to 16 Keys, certificates or data
  - Hardware support for asymmetric sign, verify, key agreement ECDSA: FIPS186-3 Elliptic Curve Digital Signature
  - ECDH: FIPS SP800-56A Elliptic Curve Diffie-Hellman
  - NIST standard P256 elliptic curve support
  - Hardware support for symmetric algorithms
  - SHA-256 & HMAC hash including off-chip context save/restore
  - AES-128: encrypt/decrypt, galois field multiply for GCM
  - Networking key management support
  - Turnkey PRF/HKDF calculation for TLS 1.2 & 1.3
  - Ephemeral key generation and key agreement in SRAM Small message encryption with keys entirely
    protected
  - Secure boot support
  - Full ECDSA code signature validation, optional stored digest/signature optional communication key disablement prior to secure boot
  - Internal high-quality FIPS 800-90 A/B/C Random Number Generator (RNG)
  - Two high-endurance monotonic counters
  - Guaranteed unique 72-bit serial number

#### MKR compatible header

- 7x PWM channels
- 7x ADC channels
- 1x SPI
- 1x UART
- 1x l2C
- ESLOV Connector
  - I2C port with automatic device enumeration
- \*\*NXP PF1550 \*\*Programmable PMIC
  - dynamic voltage scaling



- programmable independent 1A voltage output to carrier board
- programmable I/O voltage
- integrated Li-Po/Li-Ion Battery Charger



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# 2 The Board

### 2.1 Application Examples

Due to the dual core processing and the low-power capabilities, Portenta supports a wide array of applications.

**Machine Vision:** In combination with the Portenta Vision Shield it can run machine vision applications. This allows to detect the presence or movement of objects in a video stream.

**AI & Machine Learning:** Thanks to the power of the two cores it can simultaneously read data from sensors or other devices on one core while the other core processes the data stream and uses machine learning to make sense of the data. When used with the Portenta Vision Shield its camera module or the two directional microphones can be used as data sources.

**Connectivity:** The Portenta features on-board Bluetooth and Wi-Fi capabilities which makes it the perfect candidate for reliable IoT applications. When used together with the Portenta Vision Shield it enables LoRa communication in places where it needs to communicate efficiently over a long distance. The Vision Shield also features an Ethernet port that allows for wired networking applications.

#### 2.2 Accessories

The Portenta H7 Vision Shield is a rapid pathway to developing applications that combine vision, audio and connectivity. The ultra low power HM-01B0 CMOS image sensor is designed with always-on applications in mind. The 324x324 data stream can be used with either the Arduino toolchain or OpenMV for gestures, ambient light, proximity sensing, and object identification. The large pixel size (3.6µm) provides a high signal-to-noise ratio. The two omnidirectional digital-microphones (MP34DB02) allows concurrent capture of stereo sounds alongside the video stream on the MicroSD Card, as well as for beamforming uses. Connectivity is provided by either ethernet or LoRa technology. LoRa technology enables the use of this platform as part of wireless sensor network solutions.

#### 2.3 Related Products

- Portenta H7 Lite
- Portenta H7 Lite Connected

# 3 Ratings

### 3.1 Absolute Maximum

Symbol	Description	Min	Тур	Max	Unit
VINMax	Maximum input voltage from VIN pad	-0.3	-	21	V
VUSBMax	Maximum input voltage from USB connector	-0.3	-	21	V
PMax	Maximum Power Consumption	-	-	5000	mW

### 3.2 Thermal

Symbol	Description	Min	Тур	Max	Unit
TST	Storage Temperature	-40		85	°C
ТОР	Operating Temperature (excluding Wireless module)	-40		85	°C
TOPw	Operating Temperature (including Wireless module)	-10		55	°C

### 3.3 Recommended Operating Conditions

Symbol	Description	Min	Тур	Max	Unit
VIN	Input voltage from VIN pad	4.5	5	5.5	V
VUSB	Input voltage from USB connector	4.5	5	5.5	V
V3V3	3.3V output to user application		3.1		V
I3V3	3.3V output current available for user application	-	-	1000	mA
VIH	Input high-level voltage	2.31	-	3.3	V
VIL	Input low-level voltage	0	-	0.99	V
IOH Max	Current at VDD-0.4 V, output set high			8	mA
IOL Max	Current at VSS+0.4 V, output set low			8	mA
VOH	Output high voltage, 8 mA	2.7	-	3.3	V
VOL	Output low voltage, 8 mA	0	-	0.4	V

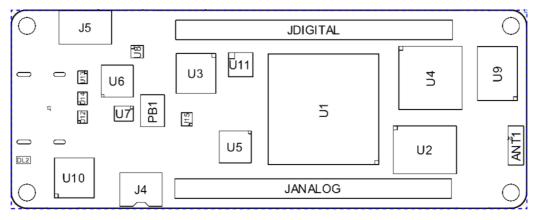


### 3.4 Power Consumption

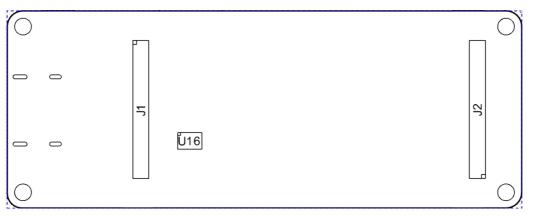
Symbol	Description	Min	Тур	Мах	Unit
PBL	Power consumption with busy loop		TBC		mW
PLP	Power consumption in low power mode		TBC		mW
PMAX	Maximum Power Consumption		TBC		mW

# 4 Functional Overview

### 4.1 Board Topology



Board Topology TOP side



Board Topology BOTTOM side

Ref.	Description	Ref.	Description
U1	STM32H747, Main processor	U10	Power Manager
U2	QSPI Flash Memory	U11	Crypto Chip (NXP)
U3	USB HS PHY	U12, U13, U14	ESD protection
U4	SDRAM	U16	Crypto Chip (Microchip)
U5	Ethernet PHY	J1, J2	High Density Connectors
U6	MIPI to USB-C/DisplayPort converter	ANT1	Antenna or U.FL Connector
U7	Level Shifter	JANALOGJDIGITAL	MKR compatible headers
U8	I2C level shifter	J4	Battery connector

Ref.	Description	Ref.	Description
U9	Wi-Fi/BT Module	J5	ESLOV connector

#### 4.2 Processor

Main processor is a dual core Cortex M7 running at up to 480 MHz and a Cortex M4 running at up to 240 MHz. The two cores communicate with each other via a hardware assisted mailbox on which Arduino implements a Remote Procedure Call mechanism that allows calling functions on the other processor seamlessly.

Both processors can share all the peripherals and resources and both can run the following applications:

- Arduino sketches on top of mbed
- Native mbed applications
- MicroPython/Javascript interpreter
- TensorFlow Lite

In all combinations of applications it is possible to invoke synchronous or asynchronous API calls. For example it is possible to extend Python language with functions implemented as Arduino sketches that are executed in parallel to other python functions by the opposite core.

Processor's various power modes allow quickly switching between high performance and very low power configurations, optimizing power consumption whenever cores are idle.

Internal memory is composed of 2MB of flash with read while write support and 1MB of RAM partitioned as follows:

- 192 Kbytes of Tightly Coupled Memory for time critical routines
  - 64 Kbytes instruction
  - 128 Kbytes of data
- 864 Kbytes of user SRAM
- 4 Kbytes of SRAM in Backup domain

#### 4.3 Wireless Module

The on board wireless module allows simultaneous management of Wi-Fi and Bluetooth connectivity. The Wi-Fi interface can be operated as an Access Point, as a Station or as a dual mode simultaneous AP/STA and can handle up to 65 Mbps transfer rate. Bluetooth interface supports Bluetooth Classic and BLE.

#### 4.4 External Memories

Optionally Portenta H7 is available with additional external SDRAM and QSPI Flash memories.

External SDRAM can provide up to 64 MByte directly mapped in CPU addressing space and allows code execution.

External QSPI flash can provide up to 128MByte of storage and can be either memory mapped for code execution (read only) or used as a QSPI peripheral for data storage.

#### 4.5 Crypto Chips

Portenta H7 provides two different optional Crypto Chip choices. The classic ATECC608A from Microchip provides low cost backwards compatibility with Arduino applications while the more advanced SE050C2 from NXP provides Common Criteria certification, larger storage memory and more advanced functionalities.

#### 4.6 Ethernet Phy

The optional 10/100 Ethernet physical interface is directly connected to the internal Ethernet MAC and provides full duplex communication with automatic MDIX support. The Wake On Lan functionality allows reducing power consumption when in sleep mode.

#### 4.7 High Speed USB Phy

The optional High Speed USB Phy is one of the two USB interfaces available on the high speed connectors and is also available on the USB-C connector. High Speed USB PHY allows transfer rates of up to 480 Mbps and can be used both as a host and as a device.

When using the USB-C connector only one USB port is usable on high speed connectors.

When the High Speed USB Phy option is not assembled the USB-C port only one Full Speed port is available and is shared between USB-C and High Density connectors

#### 4.8 USB-C Connector

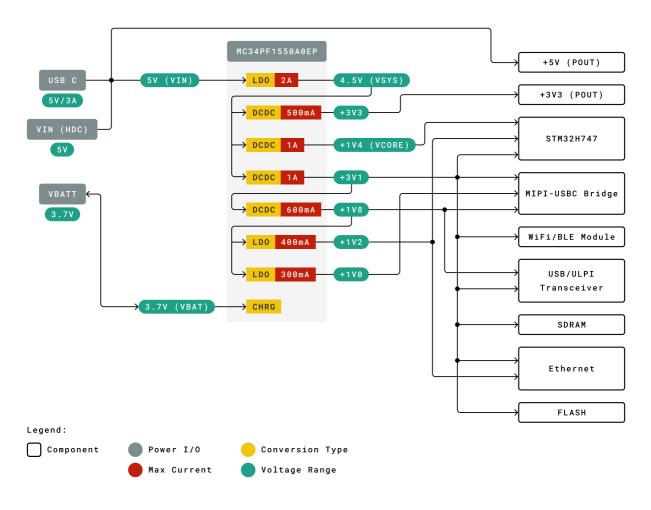
USB-C connector supports multiple use case scenarios and provides the following functions:

- Provide board power supply in both DFP and DRP mode
- Source power to external peripherals when board is powered through VIN
- expose High Speed (480Mbps) or Full Speed (12 Mbps) USB Host/Device interface
- expose DisplayPort output interface (optional)

The DisplayPort interface is usable in conjunction with USB and can be either used with a simple cable adapter when board is powered via VIN or with dongles able to provide power to the board while simultaneously outputting DisplayPort and USB. Such dongles usually provide an ethernet over USB port, a 2 port USB hub and a USB-C port that can be used to provide power to the system.

#### 4.9 Power Tree

All power conversion on the Portenta H7 is handled by the PF1550 PMIC. Current is drawn by VUSB, VIN or VBATT automatically according to rules specified by the PMIC. The VCC is driven by a buck converter configured to provide 3V3 that is accessible on both the MKR headers and the HDR connector. Two other buck converters provide 3V1 and 2V8 outputs. Additionally, three precision LDO provide low-ripple outputs of 1V0, 1V2 and 1V8. Voltage range and max current are provided as a general guideline only. Consult the PF1550 datasheet for specific details.



Portenta H7 Power Tree

# 5 Board Operation

#### 5.1 Getting Started - IDE

If you want to program your Arduino Portenta H7 while offline you need to install the Arduino Desktop IDE **[1].** To connect the Arduino Portenta H7 to your computer, you'll need a USB-C cable. This also provides power to the board, as indicated by the LED.

#### 5.2 Getting Started - Arduino Web Editor (Create)

All Arduino and Genuino boards, including this one, work out-of-the-box on the Arduino Web Editor **[2]**, by just installing a simple plugin.

The Arduino Web Editor is hosted online, therefore it will always be up-to-date with the latest features and support for all boards. Follow **[3]** to start coding in the browser and upload your sketches onto your board.

#### 5.3 Getting Started - Arduino IoT Cloud

All Arduino IoT enabled products are supported on Arduino IoT Cloud which allows you to log, graph and analyze sensor data, trigger events, and automate your business or your personal environment.

#### 5.4 Sample Sketches

Sample sketches for the Arduino Portenta H7 can be found either in the "Examples" menu in the Arduino IDE or in the "Documentation" section of the Arduino Pro website **[5]**.

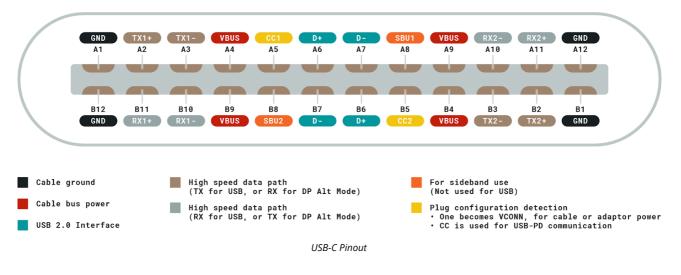
#### 5.5 Online Resources

Now that you have gone through the basics of what you can do with the board you can explore the endless possibilities it provides by checking exciting projects on ProjectHub **[6]**, the Arduino Library Reference **[7]** and the web store **[8]** where you will be able to complement your board with sensors, actuators and more.

#### 5.6 Board Recovery

All Arduino boards have a built-in bootloader which allows flashing the board via USB. In case a sketch locks up the processor and the board is not reachable anymore via USB it is possible to enter bootloader mode by double-tapping the reset button right after power up.

# **6 Connector Pinouts**



#### 6.1 USB-C

6.2 High Density Connector

	воттом					
					J2	
ETH A+ 1 ETH A- 3				80		-79 ADC A3 -77 ADC A2
ETH B+ 5				76	-	-75 ADC A1
ETH B- 7				74 🔜 🚽	-	-73 ADC A0
9	16		ADC VREF-			-71 ADC VREF+
11				70	$\rightarrow$	- 69 VCC/+3V3
13				68		-67 PWM 5
ETH L1 17				64		-63 PWM 3
ETH L2 19				62		-61 PWM 2
VIN 21 $ ightarrow$		GND	PWM 6	69	-	-59 PWM 1
USB1 VBUS 23-		·		58	-	- 57 GND
USB1 D+ 25 USB1 D- 27		5 USBO D+ B USBO D-		56		-55 -53 SAI D0
USB1 ID 29				52		-53 SAI D0 -51 SAI FS
GND 31				50	-	-49 SAI CK
UART1 TX 33		UARTO TX	GPIO 1	48	-	47 12C2 SCL
UART1 RX 35		UARTO RX		46 🗾 📄	-	45 12C2 SDA
UART1 RTS 37		UARTO RTS		44 🔡	$\leftarrow$	- 43 VCC/+3V3
UART1 CTS 39 VIN 41→		UARTO CTS	SPI1 MOSI SPI1 MISO			- 41 - 39
12C1 SDA 43		I I2C0 SDA		38		- 39 - 37
I2C1 SD6 45		I2C0 SCL		36	-	- 35
GND 47			VCC	34 - 🤆 🚽 🕘	6	- 33 GND
CAN1 TX 49				32	<b>C</b>	- 31
CAN1 RX 51				30	<b>-</b>	- 29
VSYS 53 - (				28		-27 UART3 RX -25 UART3 TX
SDC CMD 57	58			24		- 23 VCC/+3V3
SDC D0 59				22		-21
SDC D1 61		2 I2S D0	CAM CLK	29	-	- 19
SDC D2 63				18 🗾	<b>—</b>	- 17
SDC D3 65	66			16	-	- 15
67				14 <b></b>		- 13 - 11
71		V-SDCARD		10	-	- 9
RESET 73	- 74		CAM D4	8	-	7 COINCELL
SWDIO 75		i .	CAM D5	6	-	5 POWER_ON_REQ
SWCK 77	78			4		3 BOOT_SOURCE
<b>SWO</b> 79	86	1	CAM D7	2		1 FORCE_BOOTLOADER
Ground Power	Internal Pin SWD Pin Other Pin	<ul> <li>Digital Pin</li> <li>Analog Pin</li> <li>Default</li> </ul>		ontroller'		

High density connectors pinouts

### 6.3 MKR Headers

										ARDUINO SYMBO	L
					Battery	y		red	8A	LEDR	
					Battery Charger	LED RGB	LED	green	C7	LEDG	
								blue	D7	LEDB	
	Li-Pe	5 3.7 V		USB Type-C —					GND		
				Temperature					PH8	I2C0 SDA	J1-44
				Sensor	th E				PH7	I2C0 SCL	J1-46
							a <b>ta ki</b> ng p		- PI0	SPI1 CS	J2-36
				+		-1	<u>8 o</u>	>	+5V		
		AREF		AREF			C	→- +5V			
	J2-73	ADC A0	PA0_C	A0 D15	-0 .			VIN			
	J2-75	ADC A1	PA1_C	A1 D16	-0			→- +3V3			
	J2-77	ADC A2	PC2_C	A2 D17			l⁼ <u>C</u>	GND			
	J2-79	ADC A3	PC3_C	A3 D18	-0	ü		RESET	NRST		
	J2-74	ADC A4	PC2	A4 D19				D14	PA9	UART1 TX	J1-33
	J2-76	ADC A5	PC3	A5 D20				+ D13 +		UART1 RX	J1-35
	J2-78	ADC A6	PA4	A6 D21	<b>) S</b>	M32H747XIH		D12	PH7	I2C0 SCL	J1-46
	J2-62	PWM 7	PH15	DØ				D11	PH8	I2C0 SDA	J1-44
	J2-60	PWM 6	PK1	D1				D10	PC2	SPI1 MISO	J2-40
	J2-67	PWM 5	PJ11	D2		01100		D9	PI1	SPI1 CK	J2-38
	J2-65 J2-63	PWM 4 PWM 3	PG7 PC7	D3				D8	PC3 PI0	SPI1 MOSI SPI1 CS	J2-42 J2-36
	J2-63	PWM 3 PWM 2	PC7 PC6	D4				D6	P10 PA8	PWM 1	J2-30 J2-59
	32-01	P II II Z	PCO	03		_ ==			PAO	PWH	32-39
					œ						
						11					
_						<b></b>			-		
	Ground	1	Inte	ernal Pin		Digital	Pin	Mi(	crocont	troller':	s Port
	Power		CMD	Pin		Analog	Din	μ4.	ah Dong	sity Con	nector
	Fower		3110	F T 11		Anaroy	F 111	- n1	gii Della	STCY COM	Tector
	LED		Othe	er Pin		Default					
					MKR form	at Headers pin	out				
					<b>,</b>	/ //					

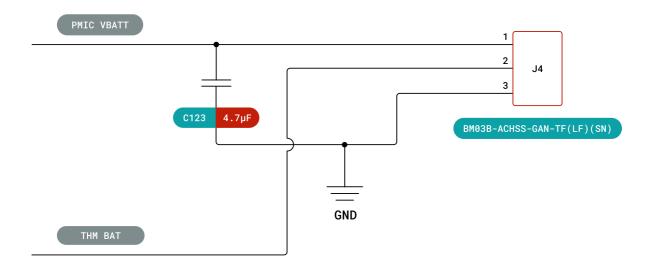
Detailed information on the Portenta H7's pinouts are available in a separate document: https://content.arduino.cc/assets/Pinout-PortentaH7\_latest.pdf



#### 6.4 Battery Connector

The Portenta H7 is compatible with a single cell Li-Po or Li-Ion battery (3.7V, 700mAh minimum) connected via a 3-pin BM03B-ACHSS-GAN-TF connector. Battery management is performed by the PF1550 IC.

#### 6.4.1 Connector Pinout



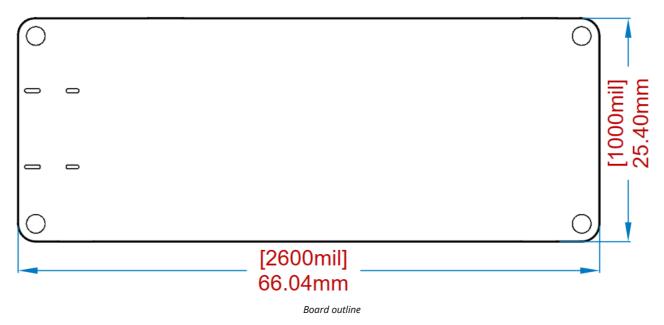
Battery pinout

#### 6.4.2 Battery Charger Specifications:

- Supports single-cell Lithium Ion/Lithium Polymer batteries
- Linear charging (10 mA to 1500 mA input limit)
- Programmable charge voltage (3.5 V to 4.44 V)
- Programmable charge current (100 mA to 1000 mA)
- Programmable charge termination current (5.0 mA to 50 mA)

# 7 Mechanical Information

### 7.1 Board Outline



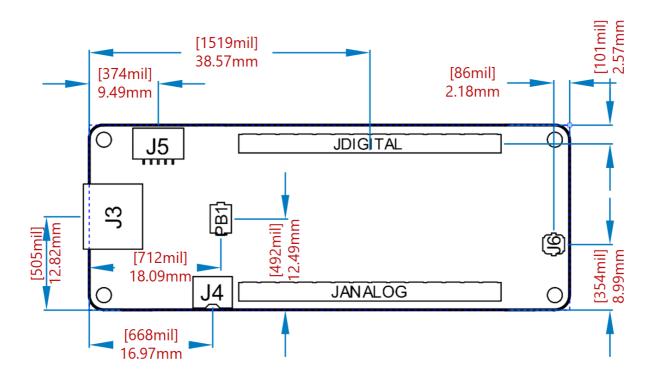
#### 7.2 Mounting Holes



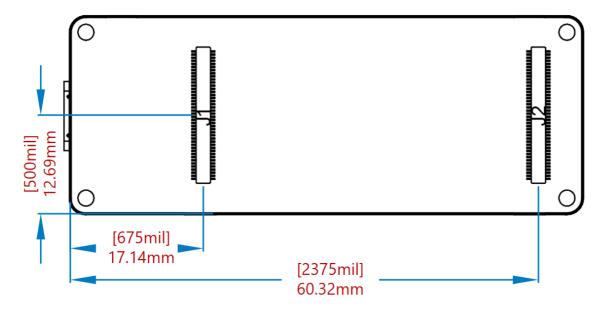
Mounting outline



### 7.3 Connector Positions



Connectors positions top



Connectors positions bottom



# 8 Certifications

#### 8.1 Declaration of Conformity CE/RED DoC (EU)

We declare under our sole responsibility that the products above are in conformity with the essential requirements of the following EU Directives and therefore qualify for free movement within markets comprising the European Union (EU) and European Economic Area (EEA).

#### Radio Equipment Directive (RED) 2014/53/EU

Conforms to: EN 300 328 v2.1.1

EN 300 328 v2.1.1

EN 300 328 v2.1.1

#### ROHS Directive 2011/65/EU

Conforms to: EN 50581:2012

#### Directive 2014/35/EU. (LVD)

Conforms to: EN 60950-1:2006/A11:2009/A1:2010/A12:2011/AC:2011

#### Directive 2004/40/EC & 2008/46/EC & 2013/35/EU, EMF

Conforms to: EN 62311:2008

The Technical Construction Files are maintained at the address shown above.

#### 8.2 Declaration of Conformity to EU RoHS & REACH 191 11/26/2018

Arduino boards are in compliance with Directive 2011/65/EU of the European Parliament and Directive 2015/863/EU of the Council of 4 June 2015 on the restriction of the use of certain hazardous substances in electrical and electronic equipment.

Substance	Maximum Limit (ppm)
Lead (Pb)	1000
Cadmium (Cd)	100
Mercury (Hg)	1000
Hexavalent Chromium (Cr6+)	1000
Poly Brominated Biphenyls (PBB)	1000
Poly Brominated Diphenyl ethers (PBDE)	1000
Bis(2-Ethylhexyl} phthalate (DEHP)	1000
Benzyl butyl phthalate (BBP)	1000
Dibutyl phthalate (DBP)	1000
Diisobutyl phthalate (DIBP)	1000

Exemptions : No exemptions are claimed.

Arduino Boards are fully compliant with the related requirements of European Union Regulation (EC) 1907 /2006 concerning the Registration, Evaluation, Authorization and Restriction of Chemicals (REACH). We declare none of



the SVHCs (https://echa.europa.eu/web/guest/candidate-list-table), the Candidate List of Substances of Very High Concern for authorization currently released by ECHA, is present in all products (and also package) in quantities totaling in a concentration equal or above 0.1%. To the best of our knowledge, we also declare that our products do not contain any of the substances listed on the "Authorization List" (Annex XIV of the REACH regulations) and Substances of Very High Concern (SVHC) in any significant amounts as specified by the Annex XVII of Candidate list published by ECHA (European Chemical Agency) 1907 /2006/EC.

#### 8.3 Conflict Minerals Declaration

As a global supplier of electronic and electrical components, Arduino is aware of our obligations with regards to laws and regulations regarding Conflict Minerals, specifically the Dodd-Frank Wall Street Reform and Consumer Protection Act, Section 1502. Arduino does not directly source or process conflict minerals such as Tin, Tantalum, Tungsten, or Gold. Conflict minerals are contained in our products in the form of solder, or as a component in metal alloys. As part of our reasonable due diligence Arduino has contacted component suppliers within our supply chain to verify their continued compliance with the regulations. Based on the information received thus far we declare that our products contain Conflict Minerals sourced from conflict-free areas.

## 9 FCC Caution

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference

(2) this device must accept any interference received, including interference that may cause undesired operation.

#### FCC RF Radiation Exposure Statement:

- 1. This Transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.
- 2. This equipment complies with RF radiation exposure limits set forth for an uncontrolled environment.
- 3. This equipment should be installed and operated with minimum distance 20cm between the radiator & your body.

English: User manuals for license-exempt radio apparatus shall contain the following or equivalent notice in a conspicuous location in the user manual or alternatively on the device or both. This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions:

(1) this device may not cause interference

(2) this device must accept any interference, including interference that may cause undesired operation of the device.

French: Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes :

(1) l' appareil nedoit pas produire de brouillage



(2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

#### IC SAR Waring:

English This equipment should be installed and operated with minimum distance 20 cm between the radiator and your body.

French: Lors de l'installation et de l'exploitation de ce dispositif, la distance entre le radiateur et le corps est d'au moins 20 cm.

**Important:** The operating temperature of the EUT can't exceed 85°C and shouldn't be lower than -40°C.

Hereby, Arduino S.r.l. declares that this product is in compliance with essential requirements and other relevant provisions of Directive 2014/53/EU. This product is allowed to be used in all EU member states.

Frequency bands	Maximum output power (ERP)	
Mhz	dBm	

# **10 Reference Documentation**

Reference	Link	
Arduino IDE	https://www.arduino.cc/en/Main/Software	
(Desktop)		
Arduino IDE (Cloud)	https://create.arduino.cc/editor	
Cloud IDE Getting	https://create.arduino.cc/projecthub/Arduino_Genuino/getting-started-with-arduino-	
Started	web-editor-4b3e4a	
Forum	http://forum.arduino.cc/	
Arduino Pro Website	https://www.arduino.cc/pro	
ProjectHub	https://create.arduino.cc/projecthub?by=part∂_id=11332&sort=trending	
Library Reference	https://www.arduino.cc/reference/en/	
Arduino Store	https://store.arduino.cc/	



# **11 Revision History**

Date	Revision	Changes
18/12/2020	1	First Release
09/08/2021	2	Updated Power Tree