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# mikroBoard for ARM 144-pin™

## User manual

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# Development system

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## 1. General information

MikroBoard for ARM 144-pin is primarily intended to be connected to the EasyARM v6 development system but can also be used as a stand-alone device. The board features the LPC2214 microcontroller, flash module, USB connector, microSD connector, JTAG connector, USB UART, voltage regulator and connectors that enable connection with the development system.

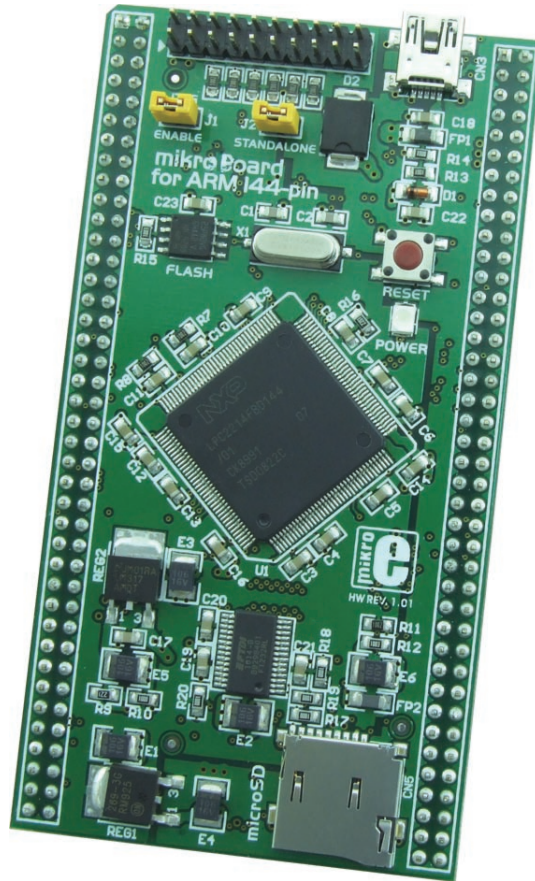


Figure 1-1: mikroBoard for ARM 144-pin



## 2. LPC2214 microcontroller

The LPC2214 microcontroller in 144-pin LQFP package is soldered on the mikoBoard for ARM 144-pin. Some of its key features are:

- 16/32-bit ARM7TDMI-S microcontroller in a LQFP144 package
- 16 kB on-chip static RAM and 256 kB on-chip flash program memory. 128-bit wide interface/accelerator enables high speed 60 MHz operation.
- In-System Programming (ISP) and In-Application Programming (IAP) via on-chip bootloader software.

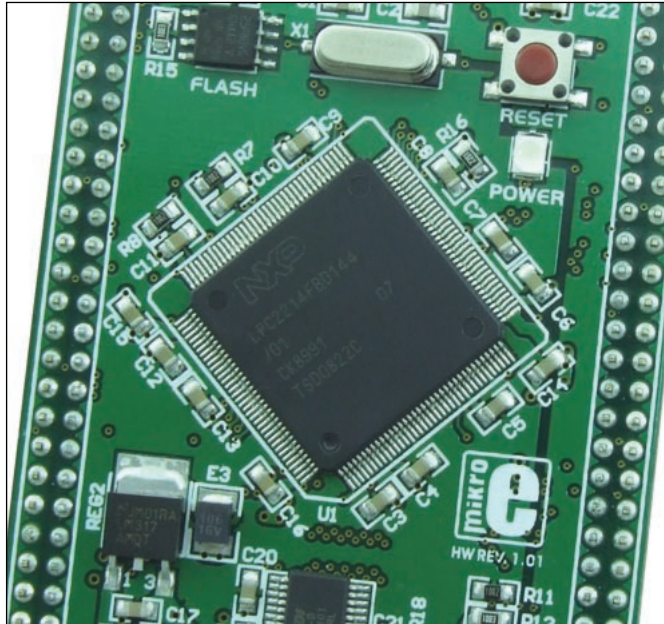


Figure 2-1: LPC2214 microcontroller

LPC2214 is connected to on board modules via pins which are also connected to CN1 and CN2 connectors. These two connectors enable the board to be connected to the EasyARM v6 development system or some other device.

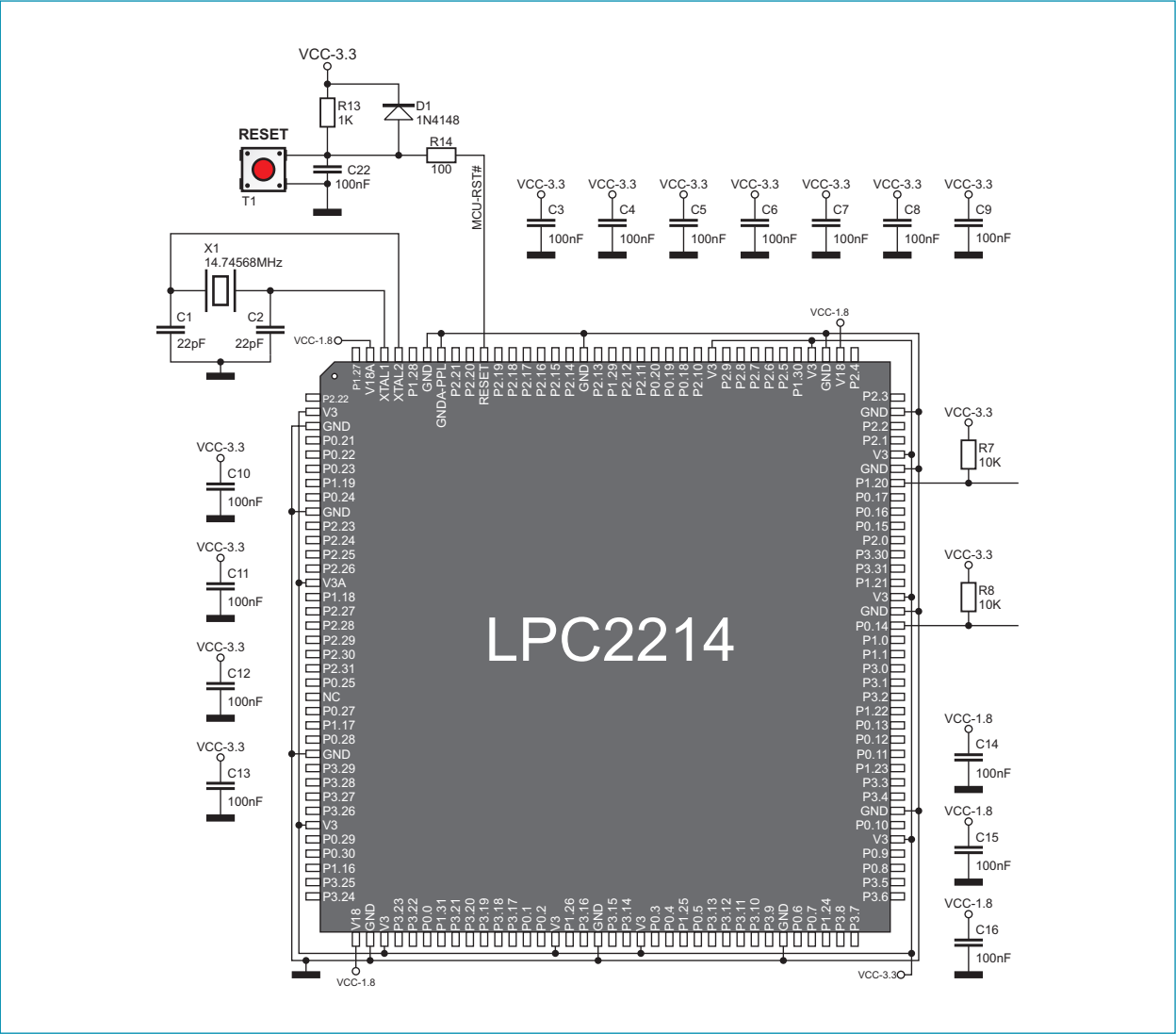
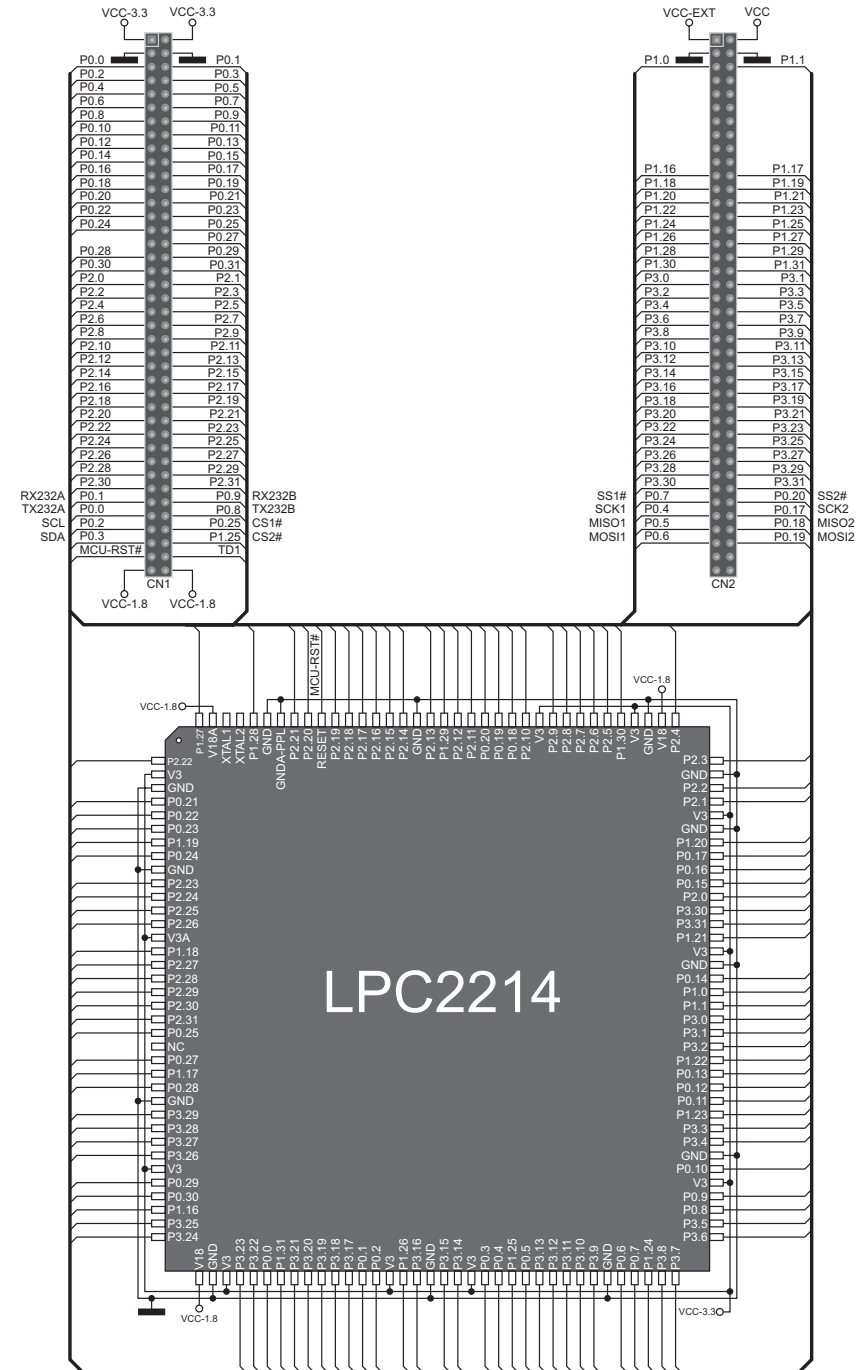


Figure 2-2: LPC2214 microcontroller with oscillators connection schematic

The LPC2214 microcontroller is connected to the X1 oscillator. The X1 oscillator generates a clock used for the operation of the microcontroller. The microcontroller can be cleared by feeding the reset pin with a logic 0, i.e. by pressing the RESET button.



**Figure 2-3:** LPC2214 microcontroller with connectors connection schematic

### 3. Programming the microcontroller

The microcontroller can be programmed with a bootloader or the JTAG programmer. The use of bootloader is enabled due to the bootloader code that is loaded into the microcontroller. In order to program the microcontroller with the bootloader, it is necessary to connect the board to a PC via the CN3 connector and USB cable, Figure 3-1. A .hex code is transferred from the PC to the microcontroller by using some of the bootloader programs, such as Flash Magic.

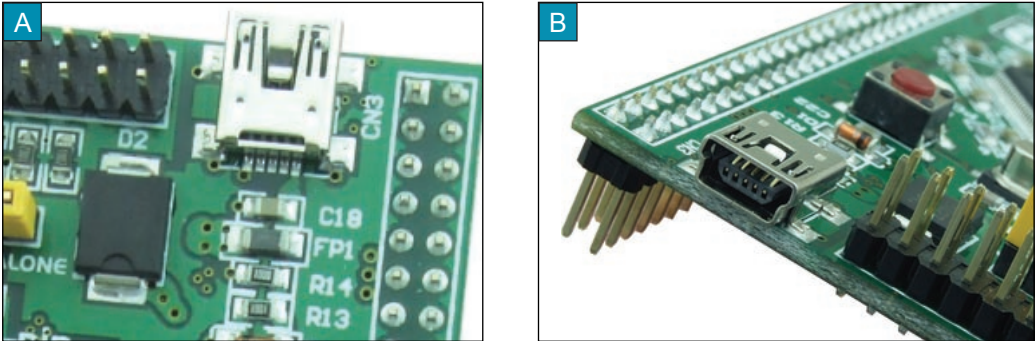


Figure 3-1: USB connector for programming

The CN3 USB connector is connected to the UART module built into the microcontroller via FTDI module (FT232RL).

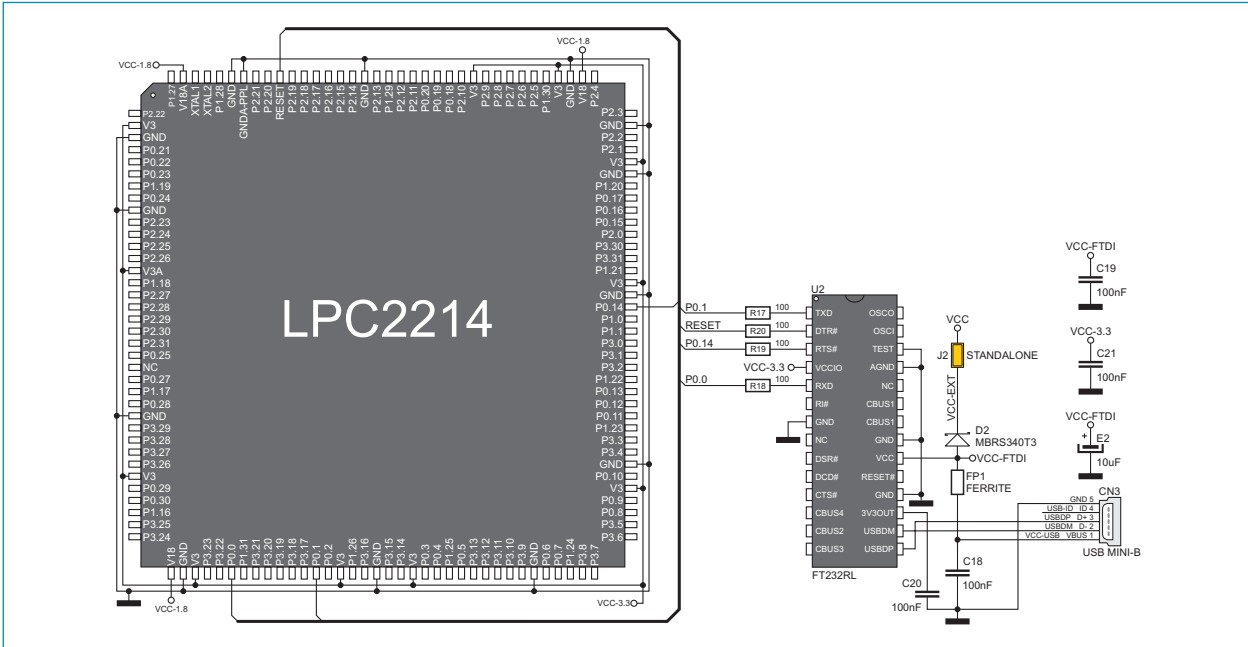


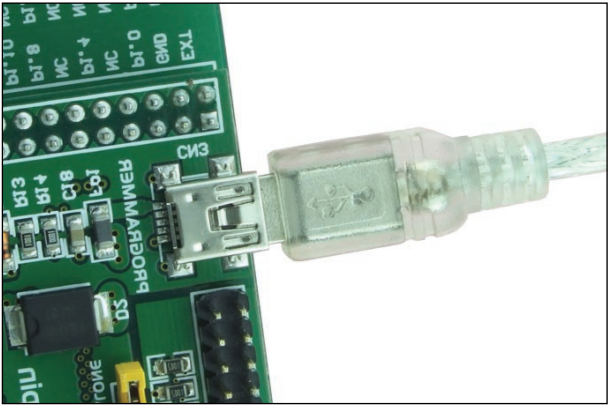
Figure 3-2: USB UART module connection schematic

When the mikroBoard for ARM 144-pin operates as a stand-alone device, it is necessary to place jumper J2 on the board. If the board is connected to the EasyARM v6 development system, jumper J2 should be removed.



In next few steps is explained how to program microcontroller with bootloader via Flash Magic application.

STEP 1: Connect the system to a PC



Connect the mikroBoard for ARM 144-pin to available USB port on your PC.

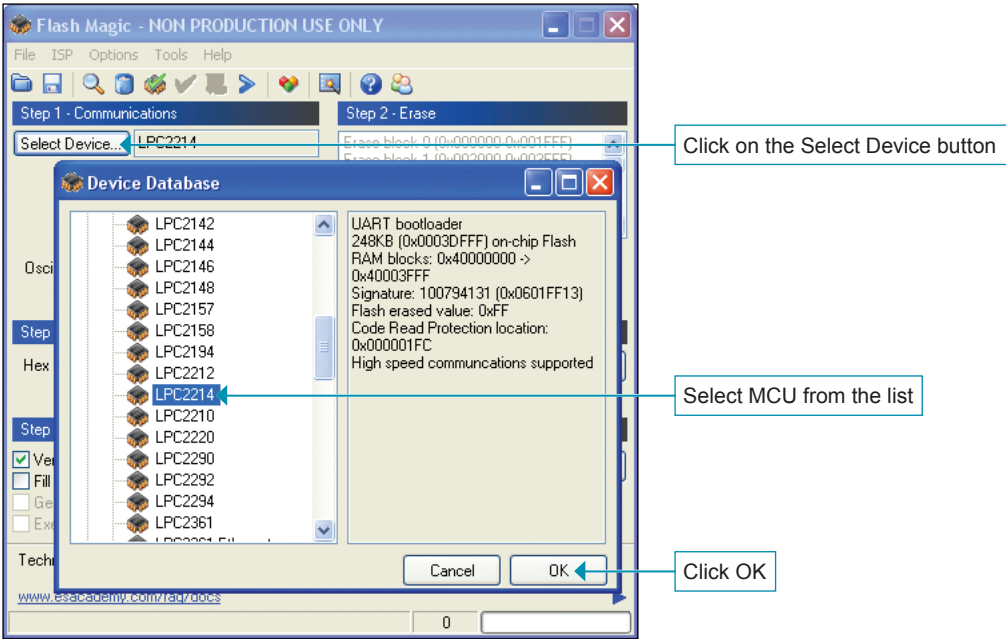
STEP 2: Start Flash Magic

Download the Flash Magic application from <http://www.flashmagictool.com/download.html&d=FlashMagic.exe> and install it on your PC

When the installation is finished double click on the Flash Magic icon



STEP 3: Select MCU



STEP 4: Settings

Step 1 - Communications

Select Device... LPC2214

COM Port: COM 5

Baud Rate: 230400

Interface: None (ISP)

Oscillator (MHz): 14.74568

Step 2 - Erase

Erase block 0 [0x000000-0x001FFF]

Erase block 1 [0x002000-0x003FFF]

Erase block 2 [0x004000-0x005FFF]

Erase block 3 [0x006000-0x007FFF]

Erase block 4 [0x008000-0x009FFF]

Erase block 5 [0x00A000-0x00BFFF]

☒ Erase all Flash+Code Rd Prot

☐ Erase blocks used by Hex file

From drop-down menu select the COM port on your PC

Set Baud Rate to 230400

Enter 14.74568 (if you use different oscillator set the appropriate value in MHz)

Device Manager on your PC contains information on which COM port is used for USB communication with the mikroBoard for ARM 144-pin development system. In this case the COM5 port is used.

Ports (COM & LPT)

Communications Port (COM1)

Printer Port (LPT1)

USB Serial Port (COM5)

Processors

Sound, video and game controllers

System devices

Universal Serial Bus controllers

Update Driver...  
Disable  
Uninstall  
Scan for hardware changes  
**Properties**

Right click on USB port, then on Properties

USB Serial Port (COM5) Properties

General Port Settings Driver Details

Bits per second: 9600

Data bits: 8

Parity: None

Stop bits: 1

Flow control: None

Advanced... Restore Defaults

From pop-up window select the Port Settings tab

Click on the Advanced... button

Advanced Settings for COM5

COM Port Number: COM5

OK Cancel Defaults

USB Transfer Sizes

Select lower settings to correct performance problems at low baud rates.

Select higher settings for faster performance.

Receive (Bytes): 4096

Transmit (Bytes): 4096

BM Options

Select lower settings to correct response problems.

Latency Timer (msec): 16

Timeouts

Minimum Read Timeout (msec): 0

Minimum Write Timeout (msec): 0

Miscellaneous Options

Serial Enumerator ☐

Serial Printer ☐

Cancel If Power Off ☐

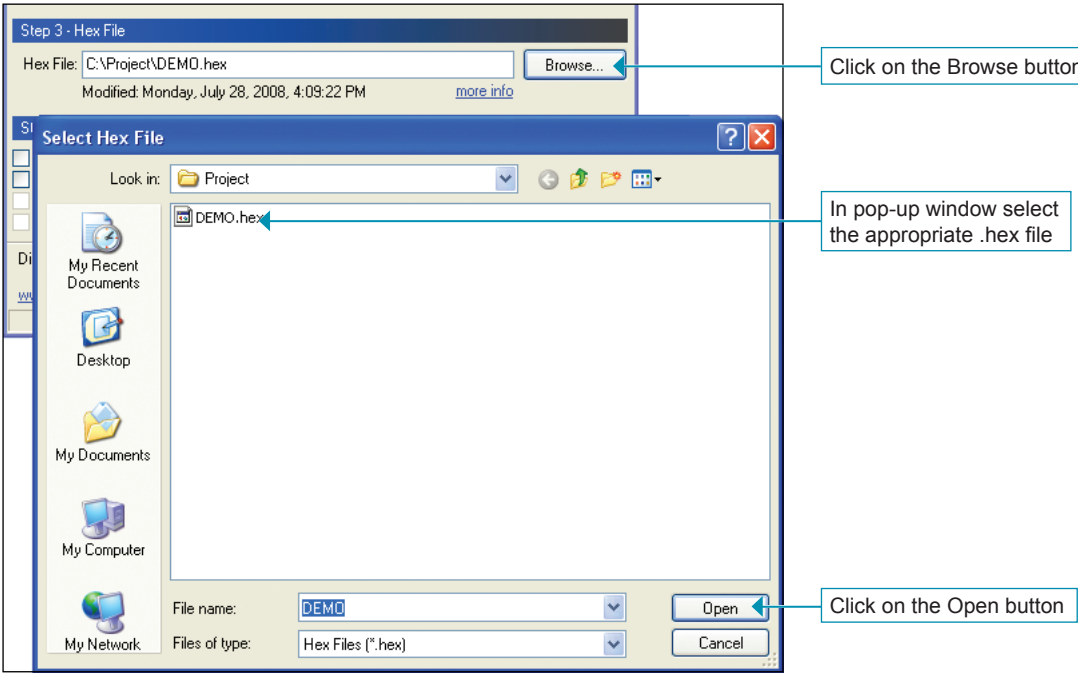
Event On Surprise Removal ☐

Set RTS On Close ☐

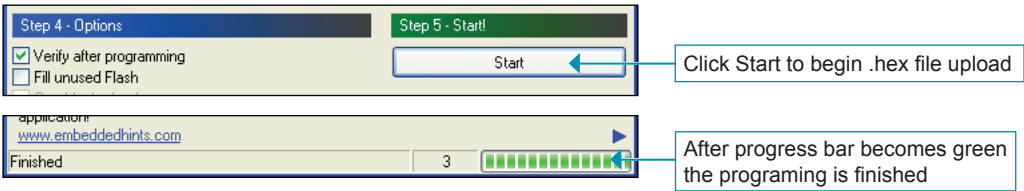
Disable Modem Ctrl At Startup ☐

In pop-up window uncheck the Serial Enumeration option and click OK

STEP 5: Browse for .hex file



STEP 6: Upload .hex file



The microcontroller can also be programmed with the JTAG programmer, Figure 3-3. In addition, this programmer can also be used to test the operation of the microcontroller.

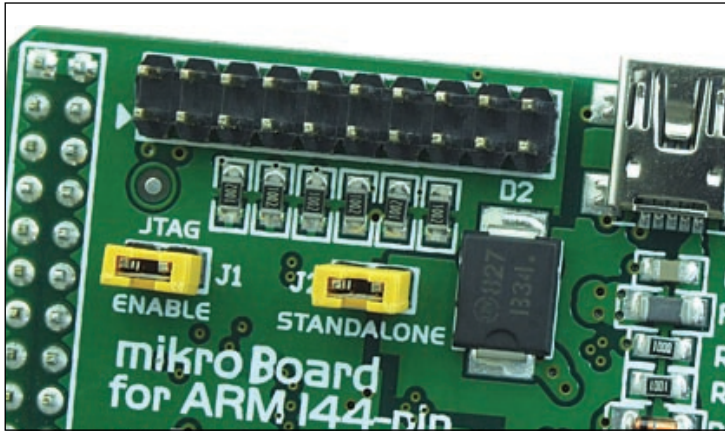


Figure 3-3: JTAG connector

In order to enable the JTAG programmer to be used, it is necessary to place jumper J1 in the ENABLE position, Figure 3-5. If the JTAG programmer is not used for programming, jumper J1 should be removed from the board, Figure 3-6.

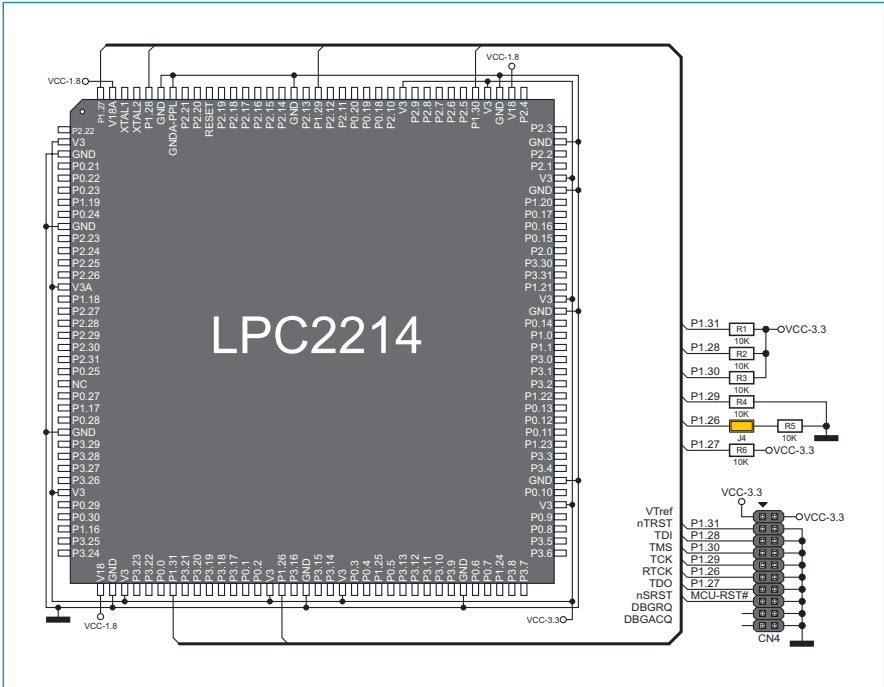


Figure 3-4: JTAG module connection schematic



Figure 3-5: JTAG is enabled

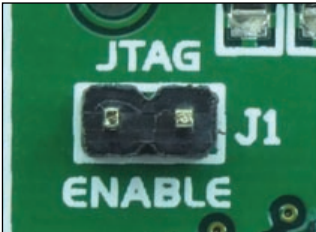


Figure 3-6: JTAG is disabled

4. Voltage regulator

The microcontroller require dual power supply: 1.8V for CPU and 3.3V for I/O. The board is powered with the 5V power supply voltage via the CN3 USB connector supplied on the board.

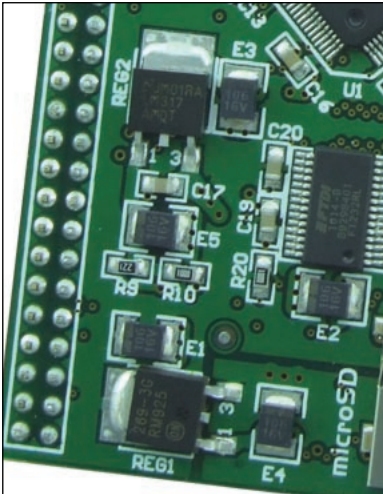


Figure 4-1: Voltage regulator

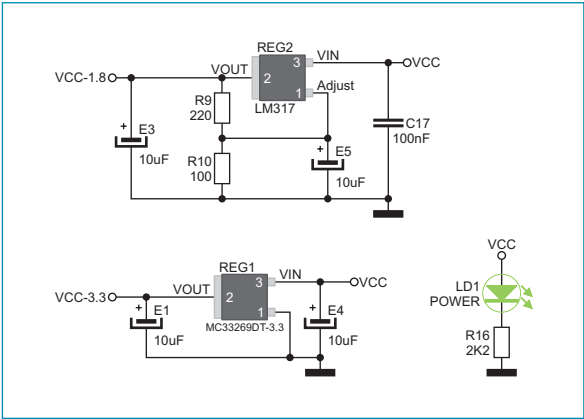


Figure 4-2: Voltage regulator connection schematic

If the board is powered by the development system (EasyARM v6), the function of the voltage regulator remains the same. In this case, it is necessary to remove jumper J2 (STANDALONE), Figure 4-3.



Figure 4-3: Standalone mode disabled

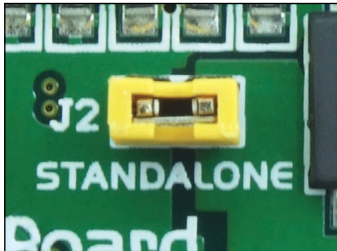


Figure 4-4: Standalone mode enabled



5. MicroSD connector

There is a connector CN5 provided on the board that enables the use of microSD card. When inserted, the microSD card provides additional memory space that the microcontroller can use to store data. Communication between the microSD card and the microcontroller is performed via the Serial Peripheral Interface (SPI).

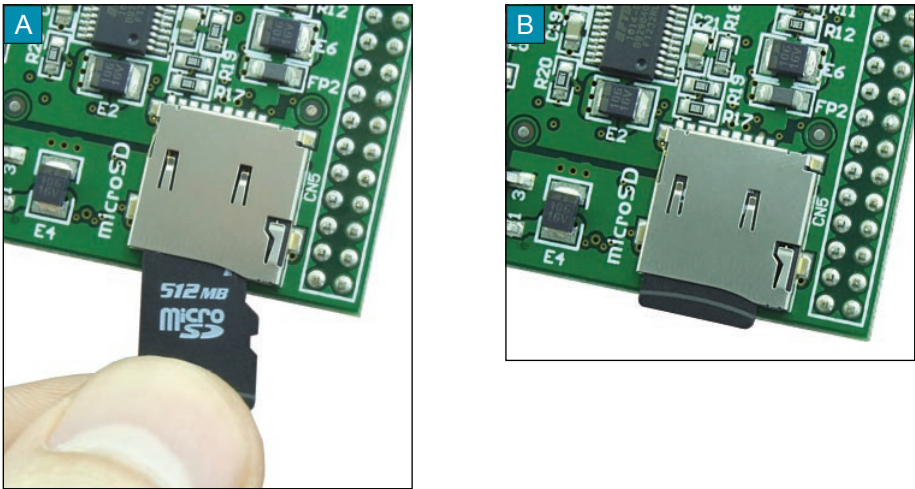


Figure 5-1: MicroSD connector

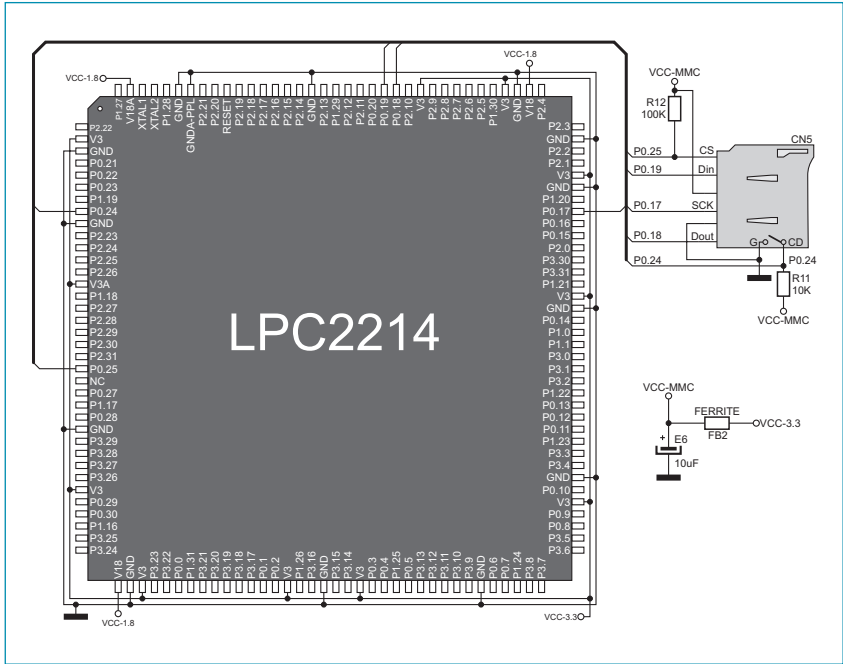


Figure 5-2: microSD connector connection schematic

The pins' designations have the following meaning:

- CS - Chip Select
- Din - Master Out/Slave In (MOSI)
- SCK - Clock
- Dout - Master In/Slave Out (MISO)

6. Flash module

Flash module provides additional 8Mbit of flash memory that the microcontroller can use via the Serial Peripheral Interface (SPI).



Figure 6-1: Flash memory

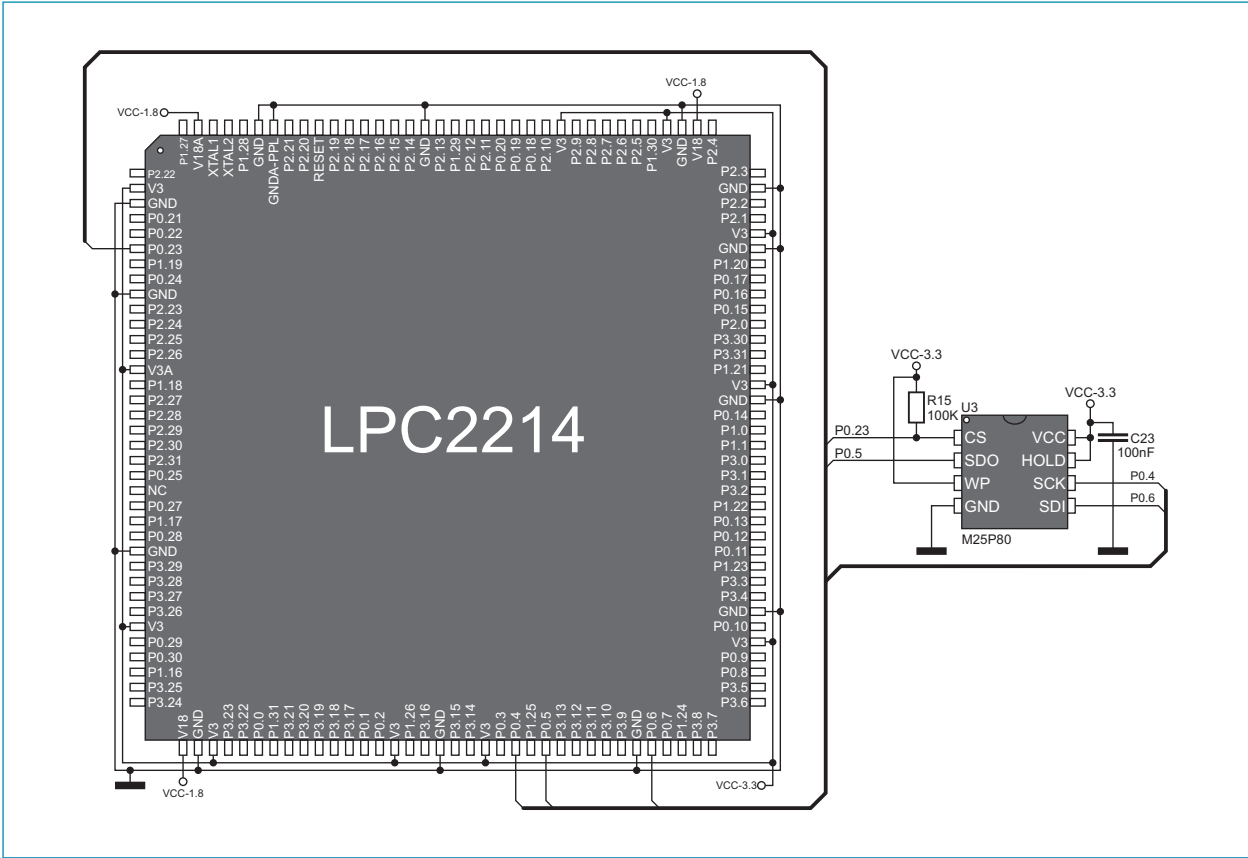


Figure 6-2: Flash module connection schematic

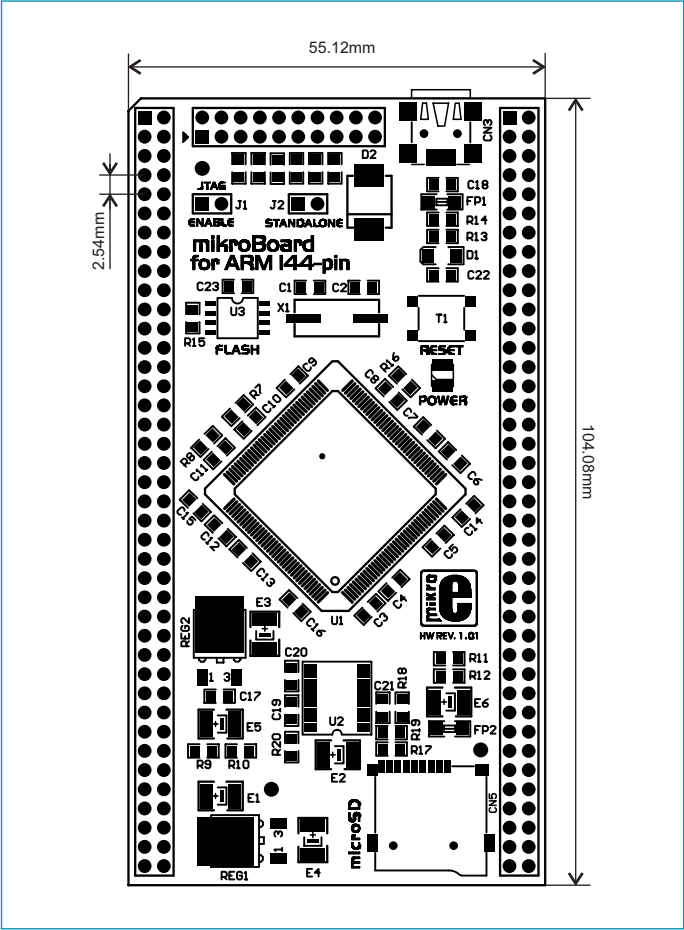


Figure 6-3: Dimensions of the mikroBoard for ARM 144-pin







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# mikroBoard for ARM 64-pin™

## User manual

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